

物理数学Iの宿題 [ver.2.1.1] の答 (一部)

ミスプリを見つけたら連絡して下さい。

§1の宿題

1.

2.

3.

$$4. \begin{pmatrix} -240 \\ 282 \\ 108 \end{pmatrix}, \begin{pmatrix} -58 \\ 118 \\ -150 \end{pmatrix}, \begin{pmatrix} -240 \\ 282 \\ 108 \end{pmatrix} + \begin{pmatrix} 182 \\ -164 \\ -258 \end{pmatrix} + \begin{pmatrix} 58 \\ -118 \\ 150 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

5. $\vec{0}$

6.

§2の宿題

$$1. \dot{k}\vec{a} + k\dot{\vec{a}}, \dot{\vec{a}} \cdot \vec{b} + \vec{a} \cdot \dot{\vec{b}}, \dot{\vec{a}} \times \vec{b} + \vec{a} \times \dot{\vec{b}}$$

2.

3.

$$4. \begin{pmatrix} 3t^2 - 4 \\ 2t + 4 \\ 16t - 9t^2 \end{pmatrix}, \begin{pmatrix} 6t \\ 2 \\ 16 - 18t \end{pmatrix}, \frac{16}{3} \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix}, \frac{2}{3} \begin{pmatrix} 2 \\ -13 \\ -22 \end{pmatrix}$$

$$5. \dot{\vec{r}} = \dot{r} \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} + r\dot{\theta} \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}, \ddot{\vec{r}} = (\ddot{r} - r\dot{\theta}^2) \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} + (2\dot{r}\dot{\theta} + r\ddot{\theta}) \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}$$

$$6. \begin{pmatrix} 6xy \\ 3x^2 - 3y^2z^2 \\ -2y^3z \end{pmatrix}, 2xz - 6y^2z^2 + xy^2, \begin{pmatrix} 2xyz + 4y^3z \\ x^2 - y^2z \\ 0 \end{pmatrix}, 6y - 6yz^2 - 2y^3, \begin{pmatrix} 2z \\ -12yz^2 - 4y^3 \\ 2xz \end{pmatrix}$$

$$7. \begin{pmatrix} 2xyz \\ x^2z \\ x^2y \end{pmatrix}, 2z^2 - z + 9xz^2, \begin{pmatrix} y \\ 4xz - 3z^3 \\ 0 \end{pmatrix}, 2yz, \begin{pmatrix} 4x \\ 0 \\ 18xz \end{pmatrix}$$

$$8. \frac{f'(r)}{r} \vec{r}, f''(r) + \frac{2}{r} f'(r)$$

$$9. rf'(r) + 3f(r), \vec{0}, f''(r)\vec{r} + 4\frac{f'(r)}{r}\vec{r}$$

$$10. \vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \frac{\vec{r}}{r}$$

$$11. \vec{E} = \frac{1}{4\pi\epsilon_0} \left(3 \frac{\vec{d} \cdot \vec{r}}{r^5} \vec{r} - \frac{1}{r^3} \vec{d} \right)$$

$$12. \vec{B} = \frac{\mu_0}{4\pi} \left(3 \frac{\vec{m} \cdot \vec{r}}{r^5} \vec{r} - \frac{1}{r^3} \vec{m} \right)$$

$$13. \pm \frac{1}{3} \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix}$$

$$14. 2\vec{a}$$

$$15. (1) \vec{\nabla} \times (\vec{\nabla} \phi) = \vec{0}, \text{rot grad } \phi = \vec{0}$$

$$(2) \vec{\nabla} \cdot (\vec{\nabla} \times \vec{a}) = 0, \text{div rot } \vec{a} = 0$$

$$(3) \vec{\nabla} \times (\vec{\nabla} \times \vec{a}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{a}) - \Delta \vec{a}, \text{rot rot } \vec{a} = \text{grad div } \vec{a} - \Delta \vec{a}$$

$$(4) \vec{\nabla}(\phi\psi) = \psi \vec{\nabla}\phi + \phi \vec{\nabla}\psi, \text{grad}(\phi\psi) = \psi \text{grad } \phi + \phi \text{grad } \psi$$

$$(5) \vec{\nabla} \cdot (\phi\vec{a}) = \vec{a} \cdot \vec{\nabla}\phi + \phi \vec{\nabla} \cdot \vec{a}, \text{div}(\phi\vec{a}) = \vec{a} \cdot \text{grad } \phi + \phi \text{div } \vec{a}$$

$$(6) \vec{\nabla} \times (\phi\vec{a}) = (\vec{\nabla}\phi) \times \vec{a} + \phi \vec{\nabla} \times \vec{a}, \text{rot}(\phi\vec{a}) = \text{grad } \phi \times \vec{a} + \phi \text{rot } \vec{a}$$

$$(7) \vec{\nabla}(\vec{a} \cdot \vec{b}) = (\vec{a} \cdot \vec{\nabla})\vec{b} + (\vec{b} \cdot \vec{\nabla})\vec{a} + \vec{a} \times (\vec{\nabla} \times \vec{b}) + \vec{b} \times (\vec{\nabla} \times \vec{a}),$$

$$\text{grad}(\vec{a} \cdot \vec{b}) = (\vec{a} \cdot \text{grad})\vec{b} + (\vec{b} \cdot \text{grad})\vec{a} + \vec{a} \times \text{rot } \vec{b} + \vec{b} \times \text{rot } \vec{a}$$

$$(8) \vec{\nabla} \cdot (\vec{a} \times \vec{b}) = (\vec{\nabla} \times \vec{a}) \cdot \vec{b} - \vec{a} \cdot (\vec{\nabla} \times \vec{b}), \text{div}(\vec{a} \times \vec{b}) = \vec{b} \cdot \text{rot } \vec{a} - \vec{a} \cdot \text{rot } \vec{b}$$

$$(9) \vec{\nabla} \times (\vec{a} \times \vec{b}) = \vec{a}(\vec{\nabla} \cdot \vec{b}) - \vec{b}(\vec{\nabla} \cdot \vec{a}) + (\vec{b} \cdot \vec{\nabla})\vec{a} - (\vec{a} \cdot \vec{\nabla})\vec{b},$$

$$\text{rot}(\vec{a} \times \vec{b}) = \vec{a} \text{div } \vec{b} - \vec{b} \text{div } \vec{a} + (\vec{b} \cdot \text{grad})\vec{a} - (\vec{a} \cdot \text{grad})\vec{b}$$

$$(10) \Delta(\phi\psi) = \psi \Delta \phi + \phi \Delta \psi + 2\vec{\nabla}\phi \cdot \vec{\nabla}\psi, \Delta(\phi\psi) = \psi \Delta \phi + \phi \Delta \psi + 2\text{grad } \phi \cdot \text{grad } \psi$$

証明は略

$$16. \vec{k} \cdot \vec{E}_0 = 0, \vec{k} \cdot \vec{B}_0 = 0, \vec{k} \times \vec{E}_0 = \omega \vec{B}_0, \vec{k} \times \vec{B}_0 = -\frac{1}{c^2} \omega \vec{E}_0. (\Rightarrow \vec{k}^2 = \frac{\omega^2}{c^2})$$

§3の宿題

法線の向きの指定のない問題では、どちらか一つの向きを選んで計算した値である。

$$1. (1) \vec{v}_0 + \begin{pmatrix} -\rho\omega \sin \omega t \\ \rho\omega \cos \omega t - \rho\omega \\ 0 \end{pmatrix} \quad (2) \vec{x}_0 + \vec{v}_0 t + \begin{pmatrix} \rho \cos \omega t - \rho \\ \rho \sin \omega t - \rho\omega t \\ 0 \end{pmatrix}$$

$$2. \frac{1}{4}M(a^2 + b^2)$$

$$3. \frac{2}{5}M \frac{a^5 - b^5}{a^3 - b^3}$$

$$4. (i) \frac{31}{6}\sqrt{3} \quad (ii) 1 + \frac{13}{2}\sqrt{2} \quad (iii) \frac{1}{6}(14\sqrt{14} - 1) \quad (iv) 0$$

$$5. (i) \frac{7}{2} \quad (ii) \frac{15}{2} \quad (iii) \frac{64}{15} \quad (iv) 0$$

$$6. (i) 2 \quad (ii) 2 \quad (iii) 2 \quad (iv) 0$$

$$7. (1) \text{rot } \vec{f} = \vec{0} \quad (2) -x^2y - xz^3 + \text{const.} \quad (3) 2$$

8. $\begin{pmatrix} \frac{8}{11} \\ \frac{4}{5} \\ 1 \end{pmatrix}$

9. $\begin{pmatrix} -\frac{9}{10} \\ -\frac{7}{3} \\ \frac{1}{5} \end{pmatrix}$

10. $\vec{B} = \frac{\mu_0 I}{4\pi} \frac{2\pi a^2}{(a^2 + z^2)^{\frac{3}{2}}} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

11. $\vec{B} = \frac{\mu_0 I}{2\pi(x^2 + y^2)} \begin{pmatrix} -y \\ x \\ 0 \end{pmatrix} = \frac{\mu_0 I}{2\pi\sqrt{x^2 + y^2}} \begin{pmatrix} \frac{-y}{\sqrt{x^2 + y^2}} \\ \frac{x}{\sqrt{x^2 + y^2}} \\ 0 \end{pmatrix}$

12. 24

13. 参考：120 = -48 + 60 + 108

14. $\begin{pmatrix} 100 \\ 100 \\ 0 \end{pmatrix}$

15. 90

16. 参考：-580 = 4π - 600 + (-4π + 20) + 0

17. 参考：π

18. 参考：2 = 0 + 0 + 0 + 2 - $\frac{1}{2}$ + $\frac{1}{2}$

19. $\frac{2}{15}$

20. 参考： $\frac{8}{3} = 0 - 1 + 0 + \frac{11}{3}$

21. 参考：84π = 36π + 0 + 48π

§4 の問題

1.

2. (1) $\vec{e}_r = \begin{pmatrix} \cos \theta \\ \sin \theta \\ 0 \end{pmatrix}$, $\vec{e}_\theta = \begin{pmatrix} -\sin \theta \\ \cos \theta \\ 0 \end{pmatrix}$, $\vec{e}_z = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$,

$$\dot{\vec{r}} = \dot{r}\vec{e}_r + r\dot{\theta}\vec{e}_\theta + \dot{z}\vec{e}_z, \quad \ddot{\vec{r}} = (\ddot{r} - r\dot{\theta}^2)\vec{e}_r + (2\dot{r}\dot{\theta} + r\ddot{\theta})\vec{e}_\theta + \ddot{z}\vec{e}_z$$

(2) $\vec{e}_r = \begin{pmatrix} \sin \theta \cos \varphi \\ \sin \theta \sin \varphi \\ \cos \theta \end{pmatrix}$, $\vec{e}_\theta = \begin{pmatrix} \cos \theta \cos \varphi \\ \cos \theta \sin \varphi \\ -\sin \theta \end{pmatrix}$, $\vec{e}_\varphi = \begin{pmatrix} -\sin \varphi \\ \cos \varphi \\ 0 \end{pmatrix}$, $\dot{\vec{r}} = \dot{r}\vec{e}_r + r\dot{\theta}\vec{e}_\theta + r \sin \theta \dot{\varphi}\vec{e}_\varphi$,

$$\ddot{\vec{r}} = (\ddot{r} - r\dot{\theta}^2 - r \sin^2 \theta \dot{\varphi}^2)\vec{e}_r + (2\dot{r}\dot{\theta} + r\ddot{\theta} - r \sin \theta \cos \theta \dot{\varphi}^2)\vec{e}_\theta + \frac{1}{r \sin \theta} \frac{d}{dt}(r^2 \sin^2 \theta \dot{\varphi})\vec{e}_\varphi$$

$$\begin{aligned}
3. (1) \quad \text{grad } \phi &= \frac{\partial \phi}{\partial r} \vec{e}_r + \frac{1}{r} \frac{\partial \phi}{\partial \theta} \vec{e}_\theta + \frac{\partial \phi}{\partial z} \vec{e}_z, \quad \text{div } \vec{a} = \frac{1}{r} \frac{\partial}{\partial r}(ra_r) + \frac{1}{r} \frac{\partial a_\theta}{\partial \theta} + \frac{\partial a_z}{\partial z}, \\
\text{rot } \vec{a} &= \left(\frac{1}{r} \frac{\partial a_z}{\partial \theta} - \frac{\partial a_\theta}{\partial z} \right) \vec{e}_r + \left(\frac{\partial a_r}{\partial z} - \frac{\partial a_z}{\partial r} \right) \vec{e}_\theta + \left(\frac{1}{r} \frac{\partial}{\partial r}(ra_\theta) - \frac{1}{r} \frac{\partial a_r}{\partial \theta} \right) \vec{e}_z, \\
\Delta \phi &= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} + \frac{\partial^2 \phi}{\partial z^2} \\
(2) \quad \text{grad } \phi &= \frac{\partial \phi}{\partial r} \vec{e}_r + \frac{1}{r} \frac{\partial \phi}{\partial \theta} \vec{e}_\theta + \frac{1}{r \sin \theta} \frac{\partial \phi}{\partial \varphi} \vec{e}_\varphi, \\
\text{div } \vec{a} &= \frac{1}{r^2 \sin \theta} \left(\sin \theta \frac{\partial}{\partial r}(r^2 a_r) + r \frac{\partial}{\partial \theta}(\sin \theta a_\theta) + r \frac{\partial a_\varphi}{\partial \varphi} \right), \\
\text{rot } \vec{a} &= \frac{1}{r^2 \sin \theta} \left(\frac{\partial}{\partial \theta}(r \sin \theta a_\varphi) - \frac{\partial}{\partial \varphi}(ra_\theta) \right) \vec{e}_r + \frac{1}{r \sin \theta} \left(\frac{\partial a_r}{\partial \varphi} - \frac{\partial}{\partial r}(r \sin \theta a_\varphi) \right) \vec{e}_\theta \\
&\quad + \frac{1}{r} \left(\frac{\partial}{\partial r}(ra_\theta) - \frac{\partial a_r}{\partial \theta} \right) \vec{e}_\varphi, \\
\Delta \phi &= \frac{1}{r^2 \sin \theta} \left(\sin \theta \frac{\partial}{\partial r} \left(r^2 \frac{\partial \phi}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \phi}{\partial \theta} \right) + \frac{1}{\sin \theta} \frac{\partial^2 \phi}{\partial \varphi^2} \right)
\end{aligned}$$

$$4. (4) \quad e = \sqrt{1 + \frac{2}{m} \left(\frac{L}{A} \right)^2} E$$

(ついでに) 線型代数の問題

問1,2,3の行列を A とおく。 P の取り方は一意的ではない。

$$1. (1) \quad P = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}, \quad A = 2 \cdot \begin{pmatrix} 2 & -2 \\ 1 & -1 \end{pmatrix} + 3 \cdot \begin{pmatrix} -1 & 2 \\ -1 & 2 \end{pmatrix}$$

$$(2) \quad P = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix},$$

$$A = 1 \cdot \begin{pmatrix} -1 & 1 & 1 \\ -1 & 1 & 1 \\ -1 & 1 & 1 \end{pmatrix} + 2 \cdot \begin{pmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 1 & -1 & 0 \end{pmatrix} + 3 \cdot \begin{pmatrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$(3) \quad P = \begin{pmatrix} -2 & -2 & -3 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix},$$

$$A = 1 \cdot \begin{pmatrix} 2 & 4 & 6 \\ 1 & 2 & 3 \\ -1 & -2 & -3 \end{pmatrix} - 1 \cdot \begin{pmatrix} -1 & -4 & -6 \\ -1 & -1 & -3 \\ 1 & 2 & 4 \end{pmatrix}$$

$$(4) \quad P = \begin{pmatrix} 1 & 1 & 0 & 1 \\ 0 & -2 & 1 & -1 \\ -1 & 0 & -1 & 0 \\ 1 & 1 & 0 & 2 \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

$$A = 0 \cdot \begin{pmatrix} 3 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ -3 & -1 & -1 & 1 \\ 3 & 1 & 1 & -1 \end{pmatrix} + 2 \cdot \begin{pmatrix} -1 & -1 & -1 & 0 \\ 2 & 2 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & -1 & -1 & 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} -1 & 0 & 0 & 1 \\ -2 & -1 & -2 & 0 \\ 3 & 1 & 2 & -1 \\ -2 & 0 & 0 & 2 \end{pmatrix}$$

$$2. (1) P = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 & 1 \\ 1 & -2 \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 9 & 0 \\ 0 & -1 \end{pmatrix}, \quad A = 9 \cdot \frac{1}{5} \begin{pmatrix} 4 & 2 \\ 2 & 1 \end{pmatrix} - 1 \cdot \frac{1}{5} \begin{pmatrix} 1 & -2 \\ -2 & 4 \end{pmatrix}$$

$$(2) P = \frac{1}{3} \begin{pmatrix} 1 & 2 & 2 \\ 2 & 1 & -2 \\ 2 & -2 & 1 \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 5 \end{pmatrix},$$

$$A = -1 \cdot \frac{1}{9} \begin{pmatrix} 1 & 2 & 2 \\ 2 & 4 & 4 \\ 2 & 4 & 4 \end{pmatrix} + 2 \cdot \frac{1}{9} \begin{pmatrix} 4 & 2 & -4 \\ 2 & 1 & -2 \\ -4 & -2 & 4 \end{pmatrix} + 5 \cdot \frac{1}{9} \begin{pmatrix} 4 & -4 & 2 \\ -4 & 4 & -2 \\ 2 & -2 & 1 \end{pmatrix}$$

$$(3) P = \begin{pmatrix} \frac{2}{3} & \frac{1}{\sqrt{5}} & \frac{4}{3\sqrt{5}} \\ -\frac{2}{3} & 0 & \frac{5}{3\sqrt{5}} \\ \frac{1}{3} & \frac{-2}{\sqrt{5}} & \frac{2}{3\sqrt{5}} \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 8 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix},$$

$$A = 8 \cdot \frac{1}{9} \begin{pmatrix} 4 & -4 & 2 \\ -4 & 4 & -2 \\ 2 & -2 & 1 \end{pmatrix} - 1 \cdot \frac{1}{9} \begin{pmatrix} 5 & 4 & -2 \\ 4 & 5 & 2 \\ -2 & 2 & 8 \end{pmatrix}$$

$$(4) P = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & -1 & -1 & 0 \\ 0 & 1 & -1 & -1 \\ 1 & 0 & 1 & -1 \\ 1 & 1 & 0 & 1 \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 3 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & -3 & 0 \\ 0 & 0 & 0 & -3 \end{pmatrix},$$

$$A = 3 \cdot \frac{1}{3} \begin{pmatrix} 2 & -1 & 1 & 0 \\ -1 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 2 \end{pmatrix} - 3 \cdot \frac{1}{3} \begin{pmatrix} 1 & 1 & -1 & 0 \\ 1 & 2 & 0 & -1 \\ -1 & 0 & 2 & -1 \\ 0 & -1 & -1 & 1 \end{pmatrix}$$

$$3. (1) P = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 0 & 0 \\ 0 & 2 \end{pmatrix}, \quad A = 0 \cdot \frac{1}{2} \begin{pmatrix} 1 & -i \\ i & 1 \end{pmatrix} + 2 \cdot \frac{1}{2} \begin{pmatrix} 1 & i \\ -i & 1 \end{pmatrix}$$

$$(2) P = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{2i}{\sqrt{6}} & \frac{i}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{-1}{\sqrt{3}} \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 3 \end{pmatrix},$$

$$A = 2 \cdot \frac{1}{2} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 1 \end{pmatrix} + 6 \cdot \frac{1}{6} \begin{pmatrix} 1 & 2i & -1 \\ -2i & 4 & 2i \\ -1 & -2i & 1 \end{pmatrix} + 3 \cdot \frac{1}{3} \begin{pmatrix} 1 & -i & -1 \\ i & 1 & -i \\ -1 & i & 1 \end{pmatrix}$$

$$(3) P = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{2i}{\sqrt{6}} & \frac{i}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & \frac{-i}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix},$$

$$A = 1 \cdot \frac{1}{3} \begin{pmatrix} 2 & i & 1 \\ -i & 2 & i \\ 1 & -i & 2 \end{pmatrix} - 2 \cdot \frac{1}{3} \begin{pmatrix} 1 & -i & -1 \\ i & 1 & -i \\ -1 & i & 1 \end{pmatrix}$$

$$(4) P = \frac{1}{2} \begin{pmatrix} 1 & \sqrt{2} & 0 & 1 \\ i & 0 & \sqrt{2} & -i \\ -1 & \sqrt{2} & 0 & -1 \\ -i & 0 & \sqrt{2} & i \end{pmatrix}, \quad P^{-1}AP = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix},$$

$$A = -1 \cdot \frac{1}{4} \begin{pmatrix} 1 & -i & -1 & i \\ i & 1 & -i & -1 \\ -1 & i & 1 & -i \\ -i & -1 & i & 1 \end{pmatrix} + 3 \cdot \frac{1}{4} \begin{pmatrix} 3 & i & 1 & -i \\ -i & 3 & i & 1 \\ 1 & -i & 3 & i \\ i & 1 & -i & 3 \end{pmatrix}$$

$$4. (1) \frac{1}{3} \begin{pmatrix} 2 & 1 & -1 \\ 1 & 2 & 1 \\ -1 & 1 & 2 \end{pmatrix} \vec{x} \quad (2) \vec{x}'$$

$$5. (1) \frac{1}{5} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{pmatrix} \vec{x} \quad (2) \vec{x}' \quad (3) \text{共に } \frac{1}{5}(x_2 + 2x_3)(y_2 + 2y_3)$$

$$6. (1) 2 \quad (2) \begin{pmatrix} 2 & -1 & 1 \\ -1 & 2 & -1 \\ 1 & -1 & 2 \end{pmatrix}, 4 \quad (4) \frac{1}{3} \begin{pmatrix} 4 & -1 & 1 \\ -1 & 4 & -1 \\ 1 & -1 & 4 \end{pmatrix}$$

$$7. (1) \frac{e^2}{2} \begin{pmatrix} e + e^{-1} & -(e - e^{-1}) \\ -(e - e^{-1}) & e + e^{-1} \end{pmatrix} \quad (2) e^\alpha \begin{pmatrix} 1 & 1 & \frac{1}{2} \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$(3) \frac{1}{6} \begin{pmatrix} e + 3e^3 + 2e^{-2} & -2e + 2e^{-2} & 3e + 3e^3 - 6e^{-2} \\ -4e + 6e^3 - 2e^{-2} & 8e - 2e^{-2} & -12e + 6e^3 + 6e^{-2} \\ -2e + 3e^3 - 2e^{-2} & 4e - 2e^{-2} & -6e + 3e^3 + 6e^{-2} \end{pmatrix}$$

$$8. (4) \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$